commands

| Id | Revision | Type | Command | Reply | Purpose | Comment |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | Date / Time | :SCMM/DD/YY\# | 0 or 1 | Set date |  |
| 2 | 0 | Date / Time | :GC\# | MM/DD/YY\# | Get date |  |
| 3 | 0 | Date / Time | SLHH:MM:SS\# | 0 or 1 | Set time (Local) |  |
| 4 | 0 | Date / Time | Ga\# | HH:MM:SS\# | Get time (Local, 12hr format) |  |
| 5 | 0 | Date / Time | :GL\# | HH:MM:SS\# | Get time (Local, 24hr format) |  |
| 6 | 0 | Date / Time | :SSHH:MM:SS\# | 0 or 1 | Set time (Sidereal) |  |
| 7 | 0 | Date / Time | GS\# | HH:MM:SS\# | Get time (Sidereal) |  |
| 8 | 0 | Site/Location | SgsHH\# | 0 or 1 | Set UTC Offset(for curent site) | The UTC Offset value is the number of hours to add to your Local Time (Standard Time) to get Universal Time. |
| 9 | 0 | Site/Location | GG\# | sHH\# | Get UTC Offset(for curent site) |  |
| 10 | 0 | Site/Location | :StsDD*MM\# | 0 or 1 | Set Latitude (for curent site) |  |
| 11 | 0 | Site/Location | Gt\# | sDD*MM\# | Get Latitude (for curent site) |  |
| 12 | 0 | Site/Location | SgDDD*MM\# | 0 or 1 | Set Longitude (for curent site) |  |
| 13 | 0 | Site/Location | :Gg\# | DDD*MM \# | Get Longitude (for curent site) |  |
| 14 | 0 | Site/Location | Smsss.... | 0 or 1 | Set site 0 name |  |
| 15 | 0 | Site/Location | :Snsss...\# | 0 or 1 | Set site 1 name |  |
| 16 | 0 | Site/Location | :Sosss...\# | 0 or 1 | Set site 2 name |  |
| 17 | 0 | Site/Location | :Spsss...\# | 0 or 1 | Set site 3 name |  |
| 18 | 0 | Site/Location | GM\# | sss...\# | Get site 0 name |  |
| 19 | 0 | Site/Location | :GN\# | sss...\# | Get site 1 name |  |
| 20 | 0 | Site/Location | :GO\# | sss...\# | Get site 2 name |  |
| 21 | 0 | Site/Location | :GP\# | sss...\# | Get site 3 name |  |
| 22 | 0 | Site/Location | Wn\# | [none] | Select site n (0-3) |  |
| 23 | 0 | Slewing/Movement | SrHH:MM:SS\# | 0 or 1* | Set target RA | * = Defaults to high precision mode, in low precision mode "HH:MM.M", "sDD*MM", or "DDD*MM" are used as appropriate. |
| 24 | 0 | Slewing/Movement | Gr\# | HH:MM:SS\#* | Get target RA |  |
| 25 | 0 | Slewing/Movement | :SdsDD:MM:SS\# | 0 or 1* | Set target Dec |  |
| 26 | 0 | Slewing/Movement | Gd\# | sDD*MM'SS\#* | Get target Dec |  |
| 27 | 0 | Slewing/Movement | :SzDDD:MM:SS\# | 0 or 1* | Set target Azm |  |
| 28 | 0 | Slewing/Movement | SasDD:MM:SS\# | 0 or 1 * | Set target Alt |  |
| 29 | 0 | Slewing/Movement | GR\# | HH:MM:SS\#* | Get telescope RA |  |
| 30 | 0 | Slewing/Movement | GD\# | sDD*MM'SS\#* | Get telescope Dec |  |
| 31 | 0 | Slewing/Movement | :GZ\# | DDD*MM'SS\#* | Get telescope Azm |  |
| 32 | 0 | Slewing/Movement | :GA\# | sDD*MM'SS\#* | Get telescope Alt |  |
| 33 | 0 | Limits | ShsDD\# | 0 or 1 | Set horizon limit | The horizon limit sets how far below (or above) the horizon the telescope will point for a goto: Valid range (in degrees) is +30 to -30 . |
| 34 | 0 | Limits | :GhsDD\# | sDD\# | Get horizon limit |  |
| 35 | 0 | Limits | :SoDD\# | 0 or 1 | Set overhead limit | The overhead limit helps keep the telescope tube from hitting the tripod etc. during a goto: Valid range (in degrees) is 60 to 90. The overhead limit helps keep the telescope tube from hitting the tripod etc. during a goto |
| 36 | 0 | Limits | GoDD\# | sDD\# | Get overhead limit |  |
| 37 | 0 | Movements | :MS\# | e*2 | Move telescope (to current Equ target) | *2 = Error codes for the MS and MA commands are as follows: $\mathrm{e}=0$ (no error), <br> $\mathrm{e}=1$ (below horizon), <br> $\mathrm{e}=2$ (no object), <br> $\mathrm{e}=4$ (position unreachable), <br> $\mathrm{e}=5$ (not aligned), <br> $\mathrm{E}=6$ (outside limits) |
| 38 | 0 | Movements | :MA\# | e*2 | Move telescope (to current Hor target) |  |
| 39 | 0 | Movements | :Q\# | [none] | Stop telescope |  |
| 40 | 0 | Movements | :Me\# | [none] | Move telescope east (at current rate) |  |
| 41 | 0 | Movements | :Mw\# | [none] | Move telescope west (at current rate) |  |
| 42 | 0 | Movements | :Mn\# | [none] | Move telescope north (at current rate) |  |
| 43 | 0 | Movements | :Ms\# | [none] | Move telescope south (at current rate) |  |
| 44 | 0 | Movements | Qe\# | [none] | Stop moving east |  |
| 45 | 0 | Movements | :Qw\# | [none] | Stop moving west |  |
| 46 | 0 | Movements | Qn\# | [none] | Stop moving north |  |
| 47 | 0 | Movements | :Qs\# | [none] | Stop moving south |  |
| 48 | 0 | Rates | :Mgdnnnn\# | [none] | (from 20 to 16399 mS ) | $\begin{aligned} & \hline \text { Pulse guide (at current rate): } \\ & \mathrm{D}=\mathrm{n}, \mathrm{~s}, \mathrm{e}, \mathrm{w}, \\ & \text { Nnnn=time in } \mathrm{mS} \text { (from } 20 \text { to } 16399 \mathrm{mS} \text { ) } \\ & \hline \end{aligned}$ |
| 49 | 0 | Rates | :RG\# | [none] | Set rate to Guide |  |
| 50 | 0 | Rates | :RC\# | [none] | Set rate to Centering |  |
| 51 | 0 | Rates | :RM\# | [none] | Set rate to Move |  |
| 52 | 0 | Rates | :RS\# | [none] | Set rate to Slew |  |
| 53 | 0 | Rates | :Rn\# | [none] | Set rate to $\mathrm{n}(0-9) * 3$ | *3 = Slew rates are as follows : <br> All values are in multipules of the sidereal rate: $\mathrm{RO}=0.25 \mathrm{X},$ <br> R1=0.5X, <br> R2(RG) $=1 \mathrm{X}$, <br> R3=2X, <br> R4(RC) $=4 \mathrm{X}$, <br> R5=8X(RM), <br> R6=16X, <br> R7(RS)=24X, <br> R8=40X, <br> R9 $=60 \mathrm{X}$ <br> (for the -Dev-Alpha branch of OnStep: <br> $\mathrm{RO}=0.25 \mathrm{X}$, <br> R1=0.5X, <br> R2(RG) $=1 \mathrm{X}$, <br> R3=2X, <br> R4=4X, <br> R5(RC) $=8 \mathrm{X}$, <br> $R 6(R M)=24 X$, <br> R7 $=48 \mathrm{X}$, <br> R8(RS) $=1 / 2$ MaxRate, <br> R9=MaxRate) |
| 54 | 0 | Pier | :D\# | 10x7F\# | Get distance bars (indicates slew) |  |
| 55 | 0 | Pier | :Gm\# | N\#, E\#or W\# | Pier side |  |

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| 56 | 0 | Tracking rate | STdd.ddddd\# | 0 or 1 | Set sidereal rate RA | Tracking rate adjustment is as follows: <br> The sidereal rate is default and is always selected on power-up. <br> The T+ and T- commands can adjust any of the rates; however only the sidereal rate, if selected, remembers the adjusted rate through a power cycle. <br> Refraction rate tracking adjusts the RA rate dynamically to best compensate for refraction in a given region of the sky; again this works for any of the rates. <br> This setting isn't remembered between power cycles, but the OnStep firmware can be compiled so that this setting defaults to enabled. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 57 | 0 | Tracking rate | GT\# | dd.ddddd\# | Get sidereal rate RA |  |
| 58 | 0 | Tracking rate | :TQ\# | [none] | Track sidereal rate RA (default) |  |
| 59 | 0 | Tracking rate | :TR\# | [none] | Track sidereal rate reset |  |
| 60 | 0 | Tracking rate | :T+\# | [none] | Track rate increase 0.02 Hz |  |
| 61 | 0 | Tracking rate | :T-\# | [ none ] | Track rate decrease 0.02 Hz |  |
| 62 | 0 | Tracking rate | :TS\# | [none] | Track solar rate RA |  |
| 63 | 0 | Tracking rate | :TL\# | [none] | Track lunar rate RA |  |
| 64 | 0 | Tracking rate | :TK\# | [none] | Track king rate RA |  |
| 65 | 0 | Tracking rate | :Te\# | 0 or 1 | Tracking enable |  |
| 66 | 0 | Tracking rate | :Td\# | 0 or 1 | Tracking disable |  |
| 67 | 0 | Tracking rate | :Tr\# | 0 or 1 | Refraction rate tracking |  |
| 68 | 0 | Tracking rate | :Tn\# | 0 or 1 | No refraction rate tracking |  |
| 69 | 0 | Sync | CS\# | [none] | Sync. with current target RA/Dec | Note: Sync's that are not allowed fail silently. This can happen due to slews, parking, or exceeded limits. |
| 70 | 0 | Sync | CM\# | N/A\# | Sync. with current target RA/Dec |  |
| 71 | 0 | Library | Lonn\# | 0 or 1 | Select catalog no. |  |
| 72 | 0 | Library | LB\# | [none] | Move Back in catalog |  |
| 73 | 0 | Library | :LN\# | [none] | Move to Next in catalog |  |
| 74 | 0 | Library | LCnnnn\# | [none] | Move to catalog item no. |  |
| 75 | 0 | Library | :L\$\# | 1 | Move to catalog name rec. |  |
| 76 | 0 | Library | Ll\# | name,type\# | Get catalog item id. |  |
| 77 | 0 | Library | :LR\# | name,type,RA,Dec\# | Read catalog item info. (also moves forward) |  |
| 78 | 0 | Library | :LWssss,ttI\# | 0 or 1 | Write catalog item info. | ssss=name, ttt=type code: UNK, OC, GC, PN, DN, SG, EG, IG, KNT, SNR, GAL, CN, STR, PLA, CMT, AST |
| 79 | 0 | Library | :LD\# | [none] | Clear current record |  |
| 80 | 0 | Library | :LL\# | [none] | Clear current cataLog |  |
| 81 | 0 | Library | :!" | [none] | Clear all catalogs | The LI\#and LW\#commands also set/get target coordinates (as with :Gr\#, :Sr\#, :Gd\#, :Sd\#) Library record storage is in EEPROM. <br> A catalog name record is like any other except the name must start with a '\$'. <br> A special search can then be done with the :L\$\#command to move to that record. It's up to the user to not waste EEPROM with more than one name record per catalog. When the default PEC table size of 824 bytes is used, the first 1024 bytes are devoted to settings. The remaining EEPROM is used for catalog records. <br> Each record is 16 bytes. <br> It's often best to divide up large Libraries into several smaller catalogs due to serial interface speed limitations. |
| 82 | 0 | Anti-backlash | :\$BRnnn\# | 0 or 1 | Set RA (Azm) backlash amount (in ArcSec) |  |
| 83 | 0 | Anti-backlash | :\$BDnnn\# | 0 or 1 | Set Dec (Alt) backlash amount (in ArcSec) |  |
| 84 | 0 | Anti-backlash | :\$QZ+\# | [none] | Turn PEC on |  |
| 85 | 0 | Anti-backlash | :\$QZ-\# | [none] | Turn PEC off |  |
| 86 | 0 | Anti-backlash | \$Qzz\# | [none] | Clear PEC data |  |
| 87 | 0 | Anti-backlash | :SQZI\#\# | [none] | Start recording PEC |  |
| 88 | 0 | Anti-backlash | :SQZ!\# | [none] | Save PEC data/settings to EEPROM |  |
| 89 | 0 | Anti-backlash | \$QZ?\# | s\# | Get PEC status returns: I-lgnore PEC, PPlaying PEC, p-Getting ready to play PEC, R-Record PEC, r-Getting ready to record PEC |  |
| 90 | 0 | Anti-backlash | :VRnnnn\# | sddd\# | Readout PEC data |  |
| 91 | 0 | Anti-backlash | :VR\# | sddd, ddd\# | Readout PEC data at current index (while playing/recording), also returns index |  |
| 92 | 0 | Anti-backlash | :WRnnnn,sddd\# | 0 or 1 | Write PEC data |  |
| 93 | 0 | Alignment | :AW\# | 0 or 1 | Align, write model to EEPROM |  |
| 94 | 0 | Alignment | A+\# | 0 or 1 | Align, accept*4 |  |
| 95 | 0 | Park / Unpark | :hQ\# | 0 or 1 | Set park position |  |
| 96 | 0 | Park / Unpark | :hP\# | 0 or 1 | Move to park position |  |
| 97 | 0 | Park / Unpark | :hR\# | 0 or 1 | Restore parked telescope to operation |  |
| 98 | 0 | Home | :hF\# | [none] | Set home (CWD) |  |
| 99 | 0 | Home | :hc\# | [none] | Move to home (CWD) |  |
| 100 | 0 | Focus | :FA\# | 0 or 1 | Focuser1 Active? |  |
| 101 | 0 | Focus | :A\# | 0 or 1 | Focuser2 Active? |  |
| 102 | 0 | Focus | :FAn\# | 0 or 1 | Select primary focuser $\mathrm{n}=1$ or 2 |  |
| 103 | 0 | Focus | :Fa\# | 0 or 1 | Get primary focuser |  |
| 104 | 0 | Focus | :FT\# | M\#or S\# | Get status M\#= moving, S\#= stopped |  |
| 105 | 0 | Focus | :FI\# | 0 or 1 | Get mode $0=$ absolute 1 = pseudo absolute |  |
| 106 | 0 | Focus | :FI\# | n\# | Get full in position (in microns or steps) |  |
| 107 | 0 | Focus | :FM\# | n\# | Get max position (in microns or steps) |  |
| 108 | 0 | Focus | :Fe\# | n\# | Get focuser temperature differential |  |
| 109 | 0 | Focus | :E\# | n\# | Get focuser temperature |  |
| 110 | 0 | Focus | :Fu\# | n.n\# | Get focuser microns per step |  |
| 111 | 0 | Focus | :FB\# | n\# | $\begin{array}{l}\text { Get focuser backlash amount (in microns or } \\ \text { steps) }\end{array}$ |  |

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| 112 | 0 | Focus | :FBn\# | 0 or 1 | Set focuser backlash amount (in microns or steps) |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 113 | 0 | Focus | :FC\# | n.n\# | Get focuser temperature compensation coefficient |  |
| 114 | 0 | Focus | :FCsn.n\# | 0 or 1 | Set focuser temperature compensation coefficient in um per deg. C (+ moves out as temperature falls) |  |
| 115 | 0 | Focus | :FC\# | 0 or 1 | Get focuser temperature compensation coefficient enable status |  |
| 116 | 0 | Focus | :Fcn\# | 0 or 1 | Enable/disable focuser temperature compensation $[\mathrm{n}]=0$ or 1 |  |
| 117 | 0 | Focus | :FD\# | n\# | Get focuser temperature compensation deadband amount (in microns or steps) |  |
| 118 | 0 | Focus | FDn\# | 0 or 1 | Set focuser temperature compensation deadband amount (in microns or steps) |  |
| 119 | 0 | Focus | :FP\# | n\# | Get focuser DC Motor Power Level (in \%) |  |
| 120 | 0 | Focus | :PPn\# | 0 or 1 | Set focuser DC Motor Power Level (in \%) |  |
| 121 | 0 | Focus | :FQ\# | [none] | Stops the focuser |  |
| 122 | 0 | Focus | :FF\# | [none] | Set focuser for fast motion ( $1 \mathrm{~mm} / \mathrm{s}$ ) |  |
| 123 | 0 | Focus | :FS\# | [none] | Set focuser for slow motion ( $0.01 \mathrm{~mm} / \mathrm{s}$ ) |  |
| 124 | 0 | Focus | :Fn\# | [none] | Set focuser move rate ( $\mathrm{n}=1$ for finest, $\mathrm{n}=2$ for $0.01 \mathrm{~mm} / \mathrm{sec}, \mathrm{n}=3$ for $0.1 \mathrm{~mm} / \mathrm{sec}, \mathrm{n}=4$ for $1 \mathrm{~mm} / \mathrm{sec}$ ) |  |
| 125 | 0 | Focus | :F+\# | [none] | Move focuser in (toward objective) |  |
| 126 | 0 | Focus | :F-\# | [none] | Move focuser out (away from objective) |  |
| 127 | 0 | Focus | :FG\# | n\# | Get focuser current position (in microns or steps) |  |
| 128 | 0 | Focus | FRsn\# | [none] | Set focuser target position relative (in microns or steps) |  |
| 129 | 0 | Focus | :FSn\# | 0 or 1 | Set focuser target position (in microns or steps) |  |
| 130 | 0 | Focus | :FZ\# | [none] | Set focuser position as zero |  |
| 131 | 0 | Focus | :FH\# | [none] | Set focuser position as half-travel |  |
| 132 | 0 | Focus | :Fh\# | [none] | Set focuser target position at half-travel |  |
| 133 | 0 | Reticle/Accessory | :B+\# | [none] | Increase reticule Brightness |  |
| 134 | 0 | Reticle/Accessory | :B-\# | [none] | Decrease reticule Brightness |  |
| 135 | 0 | Misc | :SBn\# | 0 or 1 | $\begin{aligned} & \text { Set baud rate: } 1=56.7 \mathrm{~K}, 2=38.4 \mathrm{~K}, 3=28.8 \mathrm{~K}, \\ & 4=19.2 \mathrm{~K}, 5=14.4 \mathrm{~K}, 6=9600,7=4800, \\ & 8=2400,9=1200: \text { SBn\#Reply: } 0 \text { or } 1 \end{aligned}$ |  |
| 136 | 0 | Misc | :U\# | [none] | Precision toggle |  |
| 137 | 0 | Misc | :GVD\# | MM DD YY\# | Get firmware date |  |
| 138 | 0 | Misc | :GVT\# | HH:MM:SS\# | Get firmware time |  |
| 139 | 0 | Misc | :GVN\# | 3.160\# | Get firmware number |  |
| 140 | 0 | Misc | :GVP\# | On-Step\# | Get firmware name |  |
| 141 | 0 | Misc | :GU\# | sss\# | Get Status | N Not slewing, H At Home position, P Parked, p Not parked, F Park Failed, I park In progress, RPEC Recorded |
| 142 | 0 |  | :\%BD\# |  | Return: n\# | Get Dec/Alt Antibacklash value in arc-seconds |
| 143 | 0 |  | :\%BR\# |  | Return: n \# | Get RA/Azm Antibacklash value in arc-seconds |
| 144 | 0 |  | :SBDn\# |  |  | Set Dec/Alt backlash in arc-seconds |
| 145 | 0 |  | :SBRn\# |  |  | Set RA/Azm backlash in arc-seconds |
| 146 | 0 |  | :A?\# |  | Return: mno\# | Align status |
| 147 | 0 |  | :An\# |  | Align n (0.. 9) stars | Start Telescope Manual Alignment Sequence |
| 148 | 0 |  |  |  |  |  |
| 149 | 0 |  |  |  |  |  |
| 150 | 0 |  |  |  |  | Align Write to EEPROM |
| 151 | 0 |  |  |  |  | Decrease Reticule Brightness |
| 152 | 0 |  |  |  |  | Increase reticule Brightness |
| 153 | 0 |  |  |  | Return: "N/A\#" on success, "En\#" on failure y | Synchonize the telescope with the current Wdatabase object (as above) |
| 154 | 0 |  |  |  |  | Synchonize the telescope with the current right ascension and declination coordinates |
| 155 | 0 |  | :D\# |  | Return: "l0x7f\#" if the mount is moving, other |  |
| 156 | 0 |  | :ECs\# |  |  | Echo string [c] on DebugSer. |
| 157 | 0 |  | :ENVRESET\# |  |  | Wipe flash.OnStep must be at home and tracking turned off for this command to work. |
| 158 | 0 |  | :ESPFLASH\# |  |  | ESP8266 device flash mode. OnStep must be at home and tracking turned off for this command to work. |
| 159 | 0 |  |  |  |  | Move focuser out (away from objective) |
| 160 | 0 |  |  |  |  | Set focuser move rate, where $\mathrm{n}=1$ for finest, 2 for $0.01 \mathrm{~mm} / \mathrm{sec}$ 碞, 3 for $0.1 \mathrm{~mm} /$ second, 4 for $1 \mathrm{~mm} /$ second |
| 161 | 0 |  |  |  |  | Move focuser in (toward objective) |
| 162 | 0 |  |  |  |  | Select primary focuser where [ n$]=1$ or 2 |
| 163 | 0 |  |  |  |  | Active? |
| 164 | 0 |  |  |  |  | Active? |
| 165 | 0 |  |  |  |  | Get primary focuser |
| 166 | 0 |  |  |  |  | Set focuser backlash amount (in steps or microns) |
| 167 | 0 |  |  |  | Return: n \# | Get focuser backlash amount (in steps or microns) |
| 168 | 0 |  |  |  |  | Enable/disable focuser temperature compensation where [ n ] $=0$ or 1 |
| 169 | 0 |  |  |  |  | Set focuser temperature compensation coefficient in um per deg. C (+ moves out as temperature falls) |
| 170 | 0 |  |  |  | Return: n.n\# | Get focuser temperature compensation coefficient |
| 171 | 0 |  |  |  |  | Get focuser temperature compensation enable status |
| 172 | 0 |  |  |  |  | Set focuser temperature compensation deadband amount (in steps or microns) |
| 173 | 0 |  |  |  | Return: n \# | Get focuser temperature compensation deadband amount (in steps or microns) |
| 174 | 0 |  |  |  | Return: n \#temperature in deg. C | Get focuser temperature differential |
| 175 | - |  |  |  |  | Set focuser for fast motion (1mm/s) |
| 176 | 0 |  |  |  | Return: sn\# | Get focuser current position (in microns or steps) |
| 177 | 0 |  |  |  |  | Set focuser position as half-travel |
| 178 | 0 |  |  |  |  | Set focuser target position at half-travel |
| 179 | 0 |  |  |  | Return: n\# | Get full in position (in microns or steps) |
| 180 | 0 |  |  |  | Return: n \# | Get max position (in microns or steps) |
| 181 |  |  |  |  |  | Set focuser DC Motor Power Level (in \%) |
| 182 | 0 |  | :Fp\# |  |  | Get mode |



| 268 | 0 | :RAn.n\# |  |  | Set Axis1 Guide rate to $n . n$ degrees per sidereal second |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 269 | 0 | :rbn\# |  |  |  |
| 270 | O | :rb\# |  | Return: n \# | Get rotator backlash amount in steps |
| 271 | 0 |  |  |  | Set slew rate to Centering rate 8X |
| 272 | 0 | :rC\# |  |  | Moves rotator to the home position |
| 273 | 0 | :rc\# |  |  | Set continuous move mode (for next move command) |
| 274 | 0 | :rD |  | Return: n.n\# | Get rotator degrees per step |
| 275 | 0 | :REn.n\# |  |  | Set Axis2 Guide rate to n.n degrees per sidereal second |
| 276 | 0 | :RF\# |  |  | Set slew rate to Fast Rate 48X |
| 277 | 0 | :rF\# |  |  | Reset rotator at the home position |
| 278 | 0 |  |  |  | Set slew rate to Guiding Rate 1 X |
| 279 | 0 | :rG\# |  | Return: sDDD*MM\# | Get rotator current position in degrees |
| 280 | 0 | :1\# |  | Return: n \# | Get min position (in degrees) |
| 281 | 0 |  |  |  | Set slew rate to Find Rate 20X |
| 282 | 0 | :rM\# |  | Return: n \# | Get Max position (in degrees) |
| 283 | 0 |  |  |  | Set slew rate to n , where $\mathrm{n}=0 . .9$ |
| 284 | 0 | : PP\# |  |  | Move rotator to the parallactic angle |
| 285 | 0 | :rQ\# |  |  | Stops movement (except derotator) |
| 286 | 0 | :r\# |  |  | Reverse derotator direction |
| 287 | 0 | :rSsDDD*MM'SS\# |  |  |  |
| 288 | 0 |  |  |  | Set slew rate to Half Max (VF)?X (1/2 of maxRate) |
| 289 | 0 | : T \# |  | Return: M\#(for moving) or S\#(for stopped) | Get status |
| 290 | 0 | :SasDD*MM\# |  |  |  |
| 291 | 0 |  |  |  | Set Baud Rate where n is an ASCII digit (1..9) with the following interpertation |
| 292 | 0 |  |  |  |  |
| 293 | 0 | :SdsDD*MM:SS.SSS\# |  |  |  |
| 294 | 0 | :SdsDD*MM:SS\# |  |  |  |
| 295 | 0 | :SdsDD*MM\# |  |  |  |
| 296 | 0 | :Sg(s)DDD*MM:SS.SSS |  |  |  |
| 297 | 0 | :Sg(s)DDD*MM:SS\# |  |  |  |
| 298 | 0 | :Sg(s)DDD*MM\# |  |  |  |
| 299 | 0 | :SGsHH:MM\#(where MN | M is 30 or 45)\# |  |  |
| 300 | 0 | :SGsHH\# |  |  |  |
| 301 | 0 | :ShsDD\# |  |  |  |
| 302 | 0 | :SLHH:MM:SS.SSS\# |  |  |  |
| 303 | 0 | :SLHH:MM:SS\# |  |  |  |
| 304 | 0 | :SMs\# |  |  |  |
| 305 | 0 | :SNs\# |  |  |  |
| 306 | - | :SoDD\# |  |  |  |
| 307 | 0 | :SOs\# |  |  |  |
| 308 | - | :SPs\# |  |  |  |
| 309 | 0 | :SrHH:MM:SS.SSSS\#\# |  |  |  |
| 310 | 0 | :SrHH:MM:SS\#\# |  |  |  |
| 311 | 0 | :SrHH:MM.T\#\# |  |  |  |
| 312 | 0 |  |  |  |  |
| 313 | - | :STH.H\# |  |  | Set Tracking Rate in Hz where 60.0 is solar rate |
| 314 | 0 | :StsDD*MM:SS.SSS\#\# |  |  |  |
| 315 | 0 | :StsDD*MM:SS\#\# |  |  |  |
| 316 | O | :StsDD*MM\#\# |  |  |  |
| 317 | 0 | :SXII, n\# |  |  | Set OnStep value where II is the numeric index and n is the value to set (possibly floating point) |
| 318 | 0 | :SXA1,R\# |  |  | to revert an axis to defaults |
| 319 | 0 | :SXAC,n\# |  |  | to switch between compile and run-time settings |
| 320 | 0 | :SXAn:\# |  |  | Set axis settings : SXA1,....\# |
| 321 | 0 | :SzDDD*MM\# |  |  |  |
| 322 | - |  |  |  | Master sidereal clock slower by 0.02 Hertz (stored in EEPROM) |
| 323 | 0 |  |  |  | Master sidereal clock faster by 0.02 Hertz (stored in EEPROM) |
| 324 | 0 | :T1\# |  |  | $\begin{aligned} & \text { Track single axis (disable Dec tracking on Eq } \\ & \text { mounts) } \end{aligned}$ |
| 325 | 0 | :T2\# |  |  | Track dual axis |
| 326 | 0 |  |  |  | Tracking disable |
| 327 | 0 |  |  |  | Tracking enable |
| 328 | 0 |  |  |  | Track rate king |
| 329 | 0 |  |  |  | Track rate lunar |
| 330 | 0 |  |  |  | Track refraction disable |
| 331 | 0 | :To\# |  |  | OnTrack enable |
| 332 | 0 |  |  |  | Track rate sidereal |
| 333 | 0 |  |  |  | Master sidereal clock reset (to calculated sidereal rate, stored in EEPROM) |
| 334 | 0 |  |  |  | Track refraction enable |
| 335 | 0 |  |  |  | Track rate solar |
| 336 | 0 |  |  |  | Toggle between low/hi precision positions |
| 337 | 0 | :VH\# |  | Return: n \# | PEC index sense position in seconds |
| 338 | 0 | :VRn\# |  | Return: sn\# | Read PEC table entry rate adjustment (in steps $+1-$ ) for worm segment n (in seconds) |
| 339 | 0 | :Vrn\# |  | Return: $\times 0 \times 1 \times 2 \times 3 \times 4 \times 5 \times 6 \times 7 \times 8 \times 9 \#$ (hex one by | Read out RA PEC ten byte frame in hex format starting at worm segment n (in seconds) |
| 340 | 0 |  |  | Return: sn,n\# | Read PEC table entry rate adjustment (in steps $+/-$ ) for currently playing segment and its rate adjustment (in steps $+/$-) |
| 341 | 0 | :VS\# |  | Return: n.n\# | PEC number of steps per second of worm rotation |
| 342 | 0 | :WW\# |  | Return: n\# | PEC number of steps per worm rotation |
| 343 | 0 | :W?\# |  | Return: n \# | Queries current site |
| 344 | 0 | :Wn\# |  |  | Sets current site to n , where $\mathrm{n}=0 . .3$ |
| 345 | 0 | :WR-\# |  |  | Move PEC Table back by one second |
| 346 | 0 | :WRn, sn\# |  |  | Write PEC table entry for worm segment [ n ] (in seconds) where [sn] is the correction in steps +/for this 1 second segment |
| 347 |  | :WR+\# |  |  | Move PEC Table ahead by one second |

